

Make sure to show all your work!

1. For any non-negative integer  $p$  the function

$$(x)_+^p = \begin{cases} x^p & \text{if } x > 0, \\ 0 & \text{otherwise} \end{cases}$$

is called the *truncated power function*.

Show that  $s(x) = (x-1)_+^3$  is a cubic spline and sketch its graph for  $x$  in the interval  $[0, 3]$ .

4  $s(x) = \begin{cases} s_1(x) = (x-1)^3, & x > 1 \\ s_2(x) = 0 & \text{otherwise} \end{cases}$  so the only breakpoint is at  $x=1$

Cubic spline checklist:

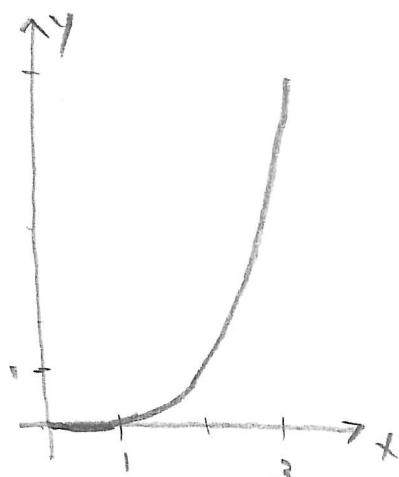
1 (1) cubic pieces: both  $s_1$  and  $s_2$  are cubic polynomials

2 (2) continuity at  $x=1$ :  $s_1(1) = (1-1)^3 = 0$  so ok  
 $s_2(1) = 0$

2 (3) continuity of  $s'$  at  $x=1$ :  $s_1'(x) = 3(x-1)^2$ ,  $s_2'(x) = 0$   
 so  $s_1'(1) = 3(1-1)^2 = 0$  ok  
 $s_2'(1) = 0$

2 (4) continuity of  $s''$  at  $x=1$ :  $s_1''(x) = 6(x-1)$ ,  $s_2''(x) = 0$   
 so  $s_1''(1) = 6(1-1) = 0$  ok  
 $s_2''(1) = 0$

4 Sketch:



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2. Consider the nonlinear equation  $x^2e^x = 1$ .

- (a) Show – using a rigorous argument – that this equation has a root in the interval  $[0, 1]$ .  
 (b) Use the secant method with initial guesses  $x_0 = 0$  and  $x_1 = 1$  to obtain the approximate root  $x_4$  (which should match the first significant digit of the “exact” solution  $x = 0.7035$ ). Use at least 6 significant digits in your calculations.

(a) First convert to a zero finding problem, i.e., find  $x$  such that

$$f(x) = x^2 e^x - 1 = 0.$$

A root in  $[0,1]$  is guaranteed by the intermediate value theorem if

$$f(0) = 0^2 e^0 - 1 = -1 < 0$$

$$\text{and } f'(1) = 1^2 e^1 - 1 = e - 1 = 1.71828 > 0$$

have different signs  $\rightarrow$  ok.

(b) The secant method is  $x_{n+1} = x_n - \frac{f(x_n) - f(x_{n-1})}{f'(x_n) - f'(x_{n-1})}$

Start with  $x_0 = 0$ ,  $x_1 = 1$ .

True

$$3 \quad x_2 = 1 - \frac{1 - 0}{\frac{f(x_0)}{f(x_1)} - 1} \approx 0.367879 \quad \text{and} \quad f(x_2) = -0.804485$$

$$x_3 = 0.367879 - \frac{0.367879 - 1}{\frac{f(x_1)}{f(x_2)} - 1} \approx 0.569456 \quad \text{and} \quad f(x_3) = -0.426897$$

$$3 \quad x_4 = 0.569456 - \frac{0.569456 - 0.361879}{\frac{f(x_2)}{f(x_3)}} = \underline{\underline{0.797357}}$$

[with  $f(x_*) = 0.4112$  (still not that close to zero)]

- ⑯ 3. Consider the three U.S. population data points taken from `censusgui.m` (here  $x$  measures years since 1900 and  $y$  is the population rounded to the nearest million):

$x$	0	10	20
$y$	76	92	106

Since population growth is often assumed to follow an exponential curve, we want to fit the data with the model  $y = ce^{\alpha x}$ .

- Apply the natural logarithm to the exponential (i.e., nonlinear) model given above to convert it to a *linear* model for an appropriately transformed set of variables.
- Use the linear model you derived in (a) to obtain a prediction for the U.S. population in the year 1925 rounded to the nearest million.

(a)  $y = ce^{\alpha x}$ , so  $\ln y = \ln(c e^{\alpha x}) = \ln c + \alpha x$

Therefore, a linear model (for  $\underline{z} = \ln y$ ) is:

$\underline{z} = \alpha x + \beta$ , where  $\beta = \ln c$  or  $c = e^\beta$

(b) The overdetermined linear system to solve is

$$\begin{matrix} 0 & 1 \\ 10 & 1 \\ 20 & 1 \end{matrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} \ln 76 \\ \ln 92 \\ \ln 106 \end{bmatrix} = \begin{bmatrix} 4.3307 \\ 4.5218 \\ 4.6634 \end{bmatrix} \Rightarrow \underline{A} \underline{c} = \underline{z}$$

with normal equations  $\underline{A}^T \underline{A} \underline{c} = \underline{A}^T \underline{z}$

$$\Rightarrow \begin{bmatrix} 500 & 30 \\ 30 & 3 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} 10 \ln 92 + 20 \ln 106 \\ \ln 76 + \ln 92 + \ln 106 \end{bmatrix} = \begin{bmatrix} 138.4867 \\ 13.5160 \end{bmatrix}$$

$$\Rightarrow \underline{\alpha = 0.0166} \text{ and } \underline{\beta = 4.3390}$$

Now  $y(x) = ce^{\alpha x} = e^\beta e^{\alpha x} = e^{\alpha x + \beta}$

so that in 1925

$$y(25) = e^{(0.0166)(25) + 4.3390} = \underline{116.1462} \approx \underline{116} \text{ (million)}$$

4. Consider the matrix

$$Q = \frac{1}{5} \begin{bmatrix} 0 & -4 & -3 \\ 4 & -\frac{9}{5} & \frac{12}{5} \\ \alpha & \beta & -\frac{16}{5} \end{bmatrix}.$$

Use the definition of an orthogonal matrix,  $Q^T Q = I$ , to find values of  $\alpha$  and  $\beta$  that make  $Q$  orthogonal.

We need to find  $\alpha$  and  $\beta$  such that  $\underline{q}_i^T \underline{q}_j = \delta_{ij}$ , where  $\underline{q}_i$  is the  $j^{\text{th}}$  column of  $\underline{Q}$ .

$$\underline{q}_1^T \underline{q}_1 = \frac{1}{25} (0 + 16 + \alpha^2) = 1 \Rightarrow \alpha = \pm 3 \quad (1)$$

$$\underline{q}_1^T \underline{q}_2 = \frac{1}{25} (0 - \frac{36}{5} + \alpha\beta) = 0 \Rightarrow \alpha\beta = \frac{36}{5} \quad (2)$$

$$\underline{q}_1^T \underline{q}_3 = \frac{1}{25} (0 + \frac{48}{5} - \frac{16\alpha}{5}) = 0 \Rightarrow 16\alpha = 48 \Rightarrow \underline{\underline{\alpha = 3}}$$

$$\text{From (2) we then get } \underline{\underline{\beta = \frac{36}{5\alpha} = \frac{12}{5}}}$$

Now we need to make sure that none of the other conditions 6 are violated if we use these values of  $\alpha$ ,  $\beta$ . ( $\underline{q}_1^T \underline{q}_1 = 1$  is ok from (1))

$$\underline{q}_2^T \underline{q}_1 = \underline{q}_1^T \underline{q}_2 = 0, \text{ so Ok}$$

$$\underline{q}_2^T \underline{q}_2 = \frac{1}{25} (16 + \frac{81}{25} + \frac{144}{25}) = \frac{1}{25} \left( \frac{400 + 81 + 144}{25} \right) = \frac{625}{625} = 1 \text{ Ok}$$

$$\underline{q}_2^T \underline{q}_3 = \underline{q}_3^T \underline{q}_2 = \frac{1}{25} (12 - \frac{108}{25} - \frac{192}{25}) = \frac{1}{25} \left( \frac{300 - 108 - 192}{25} \right) = 0 \text{ Ok}$$

$$\underline{q}_3^T \underline{q}_3 = \frac{1}{25} \left( 9 + \frac{144}{25} + \frac{256}{25} \right) = \frac{1}{25} \left( \frac{225 + 144 + 256}{25} \right) = \frac{625}{625} = 1 \text{ Ok}$$

Note that the second part is necessary.

For example, if  $\underline{q}_2 = (1, -\frac{9}{5}, \frac{12}{5})^T$  then the first part would still be true, but  $\underline{q}_2^T \underline{q}_2 = \frac{2}{5} \neq 1$  (and also  $\underline{q}_2^T \underline{q}_3 \neq 0$ ).

- 18) 5. Consider the integral  $I(f) = \int_0^1 \frac{1}{1+x^2} dx$  with "exact" value  $I(f) = 0.78539816$ .

- (a) What is the expected accuracy of the composite trapezoidal rule  $T_n$ , i.e., how do you expect the approximation error  $E_n(f) = |I(f) - T_n(f)|$  to change when you double the number of intervals used in your approximation from  $n$  to  $2n$ ?  
 (b) Illustrate your statement made for part (a) by computing trapezoidal rule approximations  $T_n$  and associated errors  $E_n$  based on  $n = 3$  and  $n = 6$  subintervals.

(a) The composite trapezoidal rule has accuracy  $O(h^2)$ , where  $h = \frac{1}{n}$ , so we should expect  $\underline{E_{2n}(f)} \approx \frac{1}{4} E_n(f)$

(b) Take  $a = 0$ ,  $b = 1$ ,  $f(x) = \frac{1}{1+x^2}$  and  $h = \frac{b-a}{n} = \frac{1}{n}$   
 as well as  $x_i = a + hi = \frac{i}{n}$ ,  $i = 0, 1, \dots, n$ ,  
 in the trapezoidal rule

$$T_n(f) = \frac{h}{2} \left[ f(x_0) + 2 \sum_{i=1}^{n-1} f(x_i) + f(x_n) \right]$$

Then

$$\begin{aligned} T_3(f) &= \frac{1}{6} \left[ f(0) + 2 \left( f\left(\frac{1}{3}\right) + f\left(\frac{2}{3}\right) \right) + f(1) \right] \\ &= \frac{1}{6} \left[ 1 + 2 \left( \frac{9}{10} + \frac{9}{13} \right) + \frac{1}{2} \right] \approx \underline{0.78076923} \end{aligned}$$

$$\text{with } E_3(f) = |I(f) - T_3(f)| = |0.78539816 - 0.78076923| = \underline{4.6289 \times 10^{-3}}$$

$$\begin{aligned} \text{and } T_6(f) &= \frac{1}{12} \left[ f(0) + 2 \left( f\left(\frac{1}{6}\right) + f\left(\frac{2}{6}\right) + f\left(\frac{3}{6}\right) + f\left(\frac{4}{6}\right) + f\left(\frac{5}{6}\right) \right) + f(1) \right] \\ &= \frac{1}{12} \left[ 1 + 2 \left( \frac{36}{37} + \frac{36}{40} + \frac{36}{45} + \frac{36}{52} + \frac{36}{61} \right) + \frac{1}{2} \right] \approx \underline{0.78424077} \end{aligned}$$

$$\text{with } E_6(f) = |I(f) - T_6(f)| = |0.78539816 - 0.78424077| = \underline{1.1574 \times 10^{-3}}$$

$$\begin{aligned} \text{Note that } \frac{E_6(f)}{E_3(f)} &= \frac{1.1574 \times 10^{-3}}{4.6289 \times 10^{-3}} = 0.2500 = \underline{\frac{1}{4}} \end{aligned}$$

6. This problem looks at the use of the SVD to obtain the least squares solution of an over-determined linear system  $\mathbf{A}\mathbf{c} = \mathbf{y}$ . Consider the following MATLAB input and output:

```

>> A = [0.3111 1.1031; 1.5556 1.2728; 1.4708 1.3576];
>> y = [1 1 1]';
>> [U S V] = svd(A)
U =
    0.3333    0.9333    0.1332
    0.6667   -0.3333    0.6667
    0.6667   -0.1334   -0.7333
S =
    3.0000      0
        0    0.6000
        0      0
V =
    0.7071   -0.7071
    0.7071    0.7071

```

What output is produced when you next execute the following code?

$$\begin{aligned}
r &= \text{length}(\text{find}(\text{diag}(S))) \quad \xrightarrow{\quad r=2 \quad} \\
\mathbf{U}_{\hat{}} &= \mathbf{U}(:,1:r) \quad \xrightarrow{\quad \mathbf{U}_{\hat{}} = \quad} \\
\mathbf{S}_{\hat{}} &= S(1:r,1:r) \quad \xrightarrow{\quad \mathbf{S}_{\hat{}} = \quad} \\
z &= \mathbf{U}_{\hat{}}^* \mathbf{y} ./ \text{diag}(\mathbf{S}_{\hat{}}) \\
c &= \mathbf{V} * z
\end{aligned}$$

Further,

$$\text{diag}(\mathbf{S}_{\hat{}}) = \begin{bmatrix} 3.0000 \\ 0.6000 \end{bmatrix}$$

$$\mathbf{U}_{\hat{}} = \begin{bmatrix} 0.3333 & 0.9333 \\ 0.6667 & -0.3333 \\ 0.6667 & -0.1334 \\ 3.0000 & 0 \\ 0 & 0.6000 \end{bmatrix}$$

$$\mathbf{U}_{\hat{}}^* \mathbf{y} = \begin{bmatrix} 0.3333 & 0.6667 & 0.6667 \\ 0.9333 & -0.3333 & -0.1334 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1.6667 \\ 0.4667 \end{bmatrix}$$

$$z = \left[ \frac{1.6667}{3} \quad \frac{0.4667}{0.6} \right]' = \begin{bmatrix} 0.5556 \\ 0.7778 \end{bmatrix}$$

$$\begin{aligned}
\text{and } c &= \begin{bmatrix} 0.7071 & -0.7071 \\ 0.7071 & 0.7071 \end{bmatrix} \begin{bmatrix} 0.5556 \\ 0.7778 \end{bmatrix} = \begin{bmatrix} -0.1571 \\ 0.9428 \end{bmatrix}
\end{aligned}$$